GPS SPOOFING ATTACK DETECTION ON INTERSECTION MOVEMENT ASSIST USING ONE CLASS CLASSIFICATION

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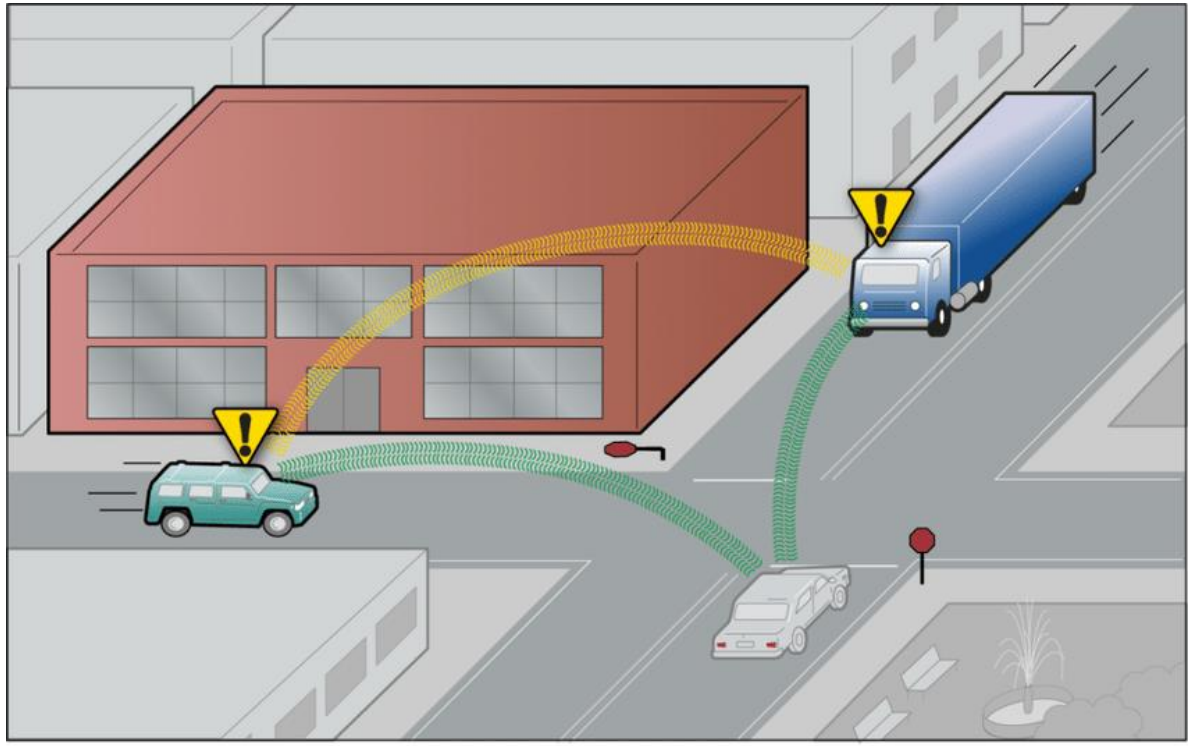
Connected, Automated, and Resilient Transportation (CART) Lab

Introduction

Overview



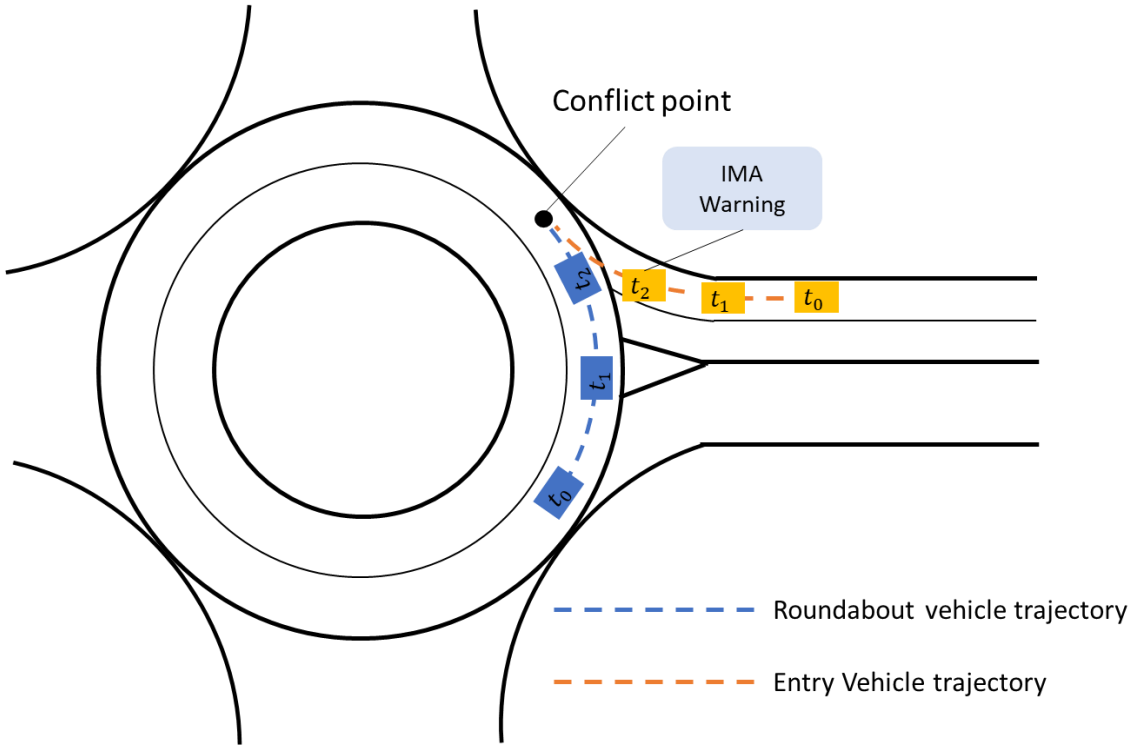
Source: GAO.

Emara, Karim. (2016). Safety-aware Location Privacy in Vehicular Ad-hoc Networks.

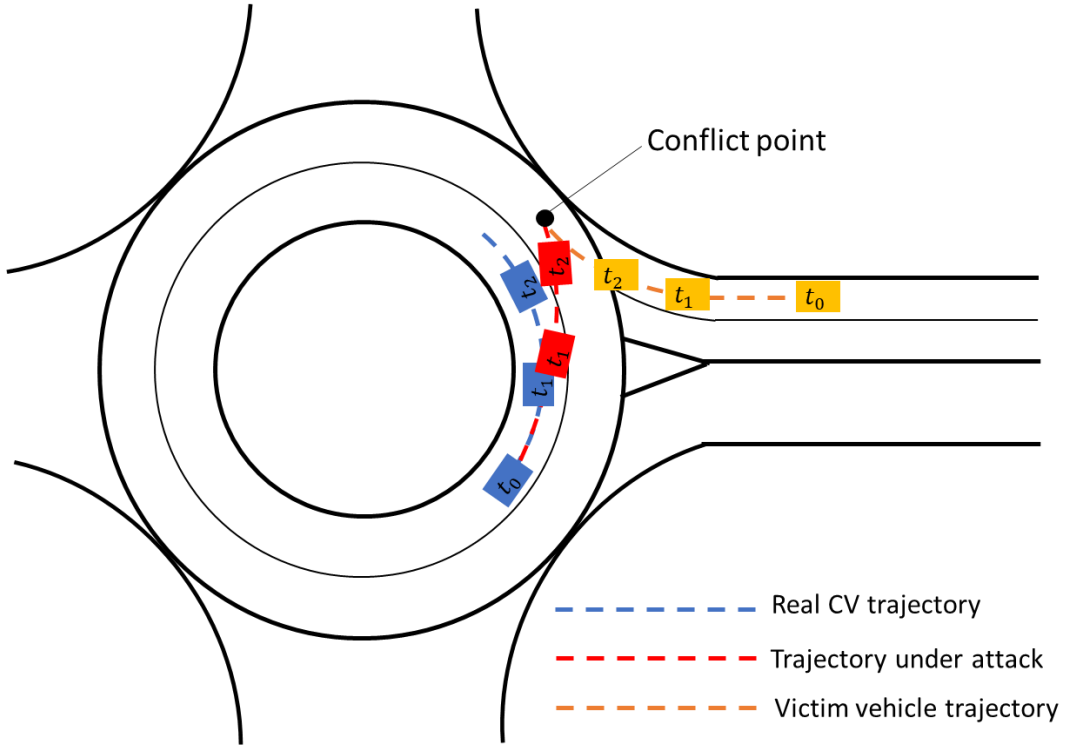
- GPS spoofing attack model
- Anomaly detection model

Threat Model

IMA warning application



CV threat model



Threat Model

Trajectory generation model

$$minimize_s\ \theta^T f(s,u) \quad (1)$$
$$s.t.$$
$$vehicle\ dynamic\ constraints$$

Objective function:

Acceleration: $f_1 = \frac{1}{N}\sum_i a_i^2.$

Heading rate : $f_2 = \frac{1}{N-1}\sum_i (\dot{\psi_i})^2.$

Curvature: $f_3 = \frac{1}{N}\sum_i \sqrt{(x_i - x^c)^2 + (y_i - y^c)^2}.$

Lateral terminal point: $f_4 = (x_N - x^{con})^2.$

Longitudinal terminal point: $f_5 = (y_N - y^{con})^2$

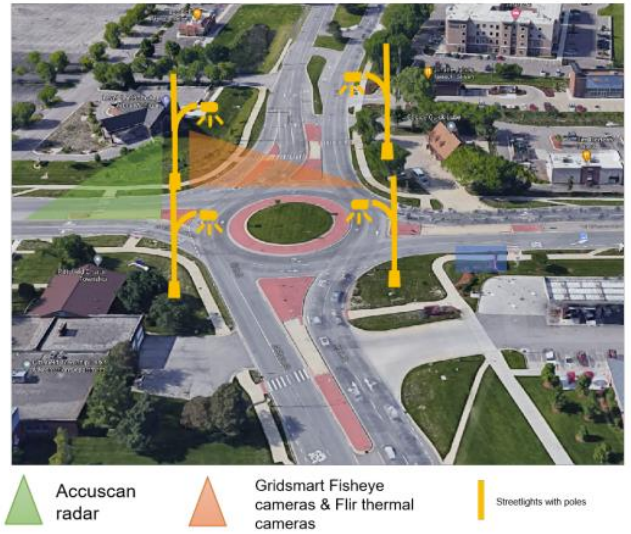
→ Generate close to realistic trajectory

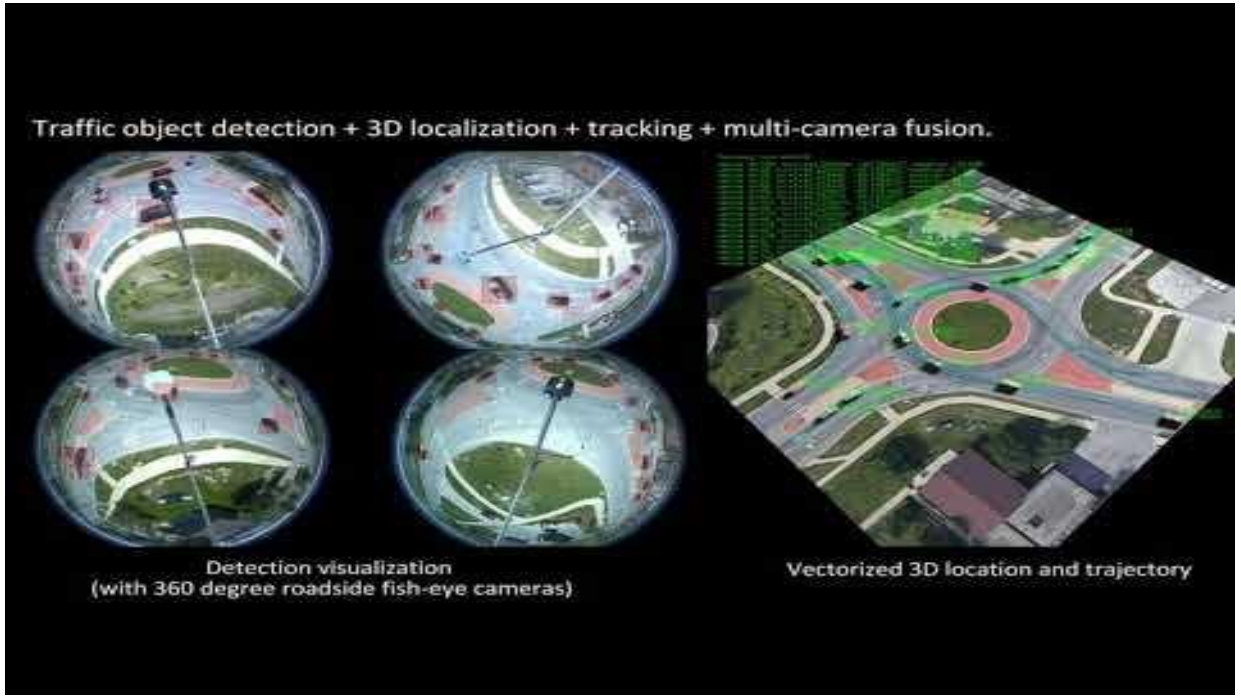
→ Trigger victim vehicle's IMA warning

Data Set Description

Trajectory data collected from the State & Ellsworth roundabout at Ann Arbor, Michigan

- Time step 0.4s
  - Vehicle location
  - Speed
  - Heading
  - Acceleration
  - Neighboring vehicle information





Video Source: Michigan Traffic Lab

Zhang R, Zou Z, Shen S, Liu HX. Design, implementation, and evaluation of a roadside cooperative perception system. Transportation research record. 2022 Nov;2676(11):273-84.

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CART

CV Threat Model Experiments

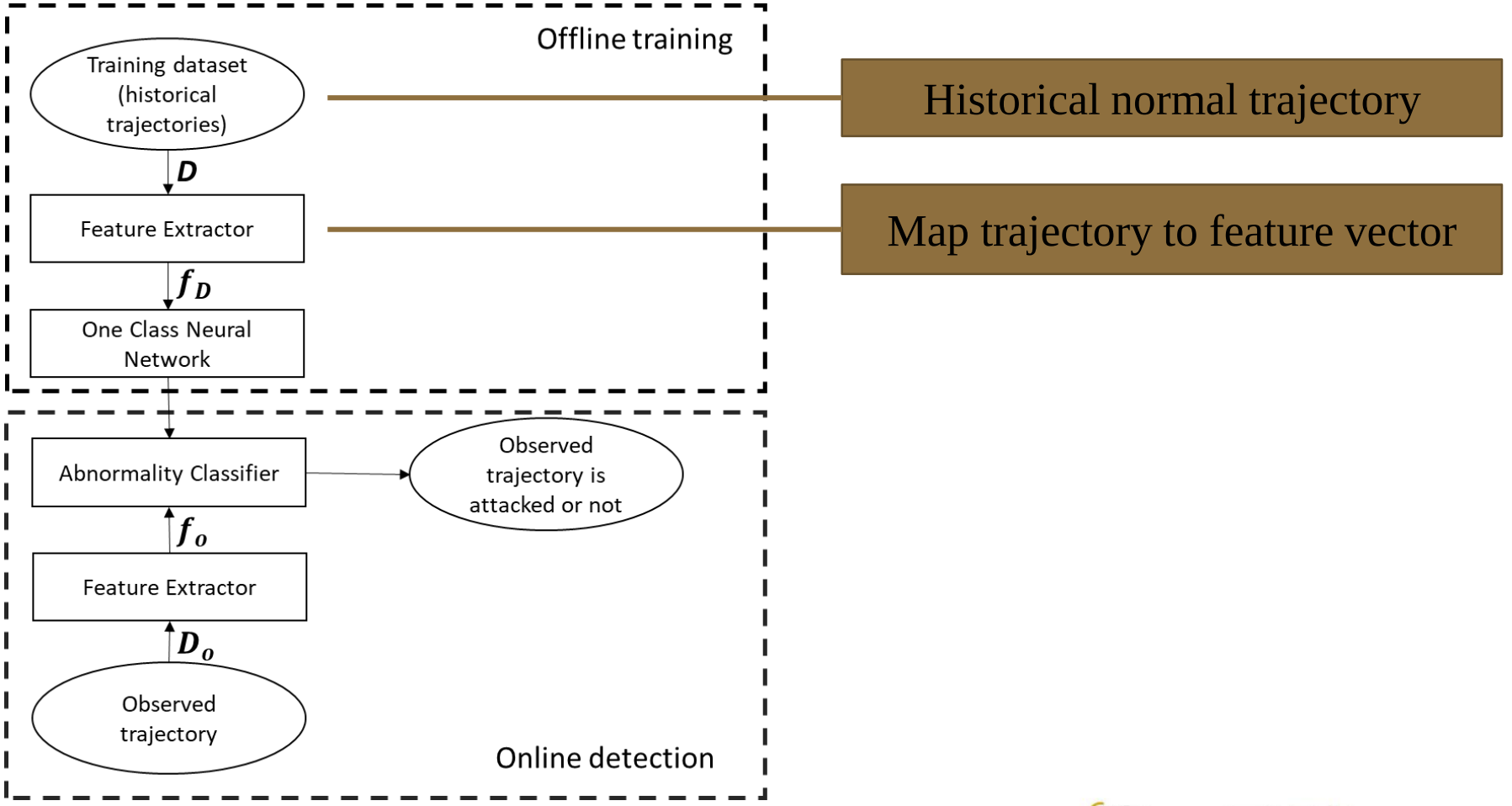
Numerical Experiments

- 927 vehicle pairs
- Attack success rate:77.970%.
- Average attack success time: 1.71s.

Real vehicle trajectory
BSM trajectory under attack
Victim vehicle trajectory

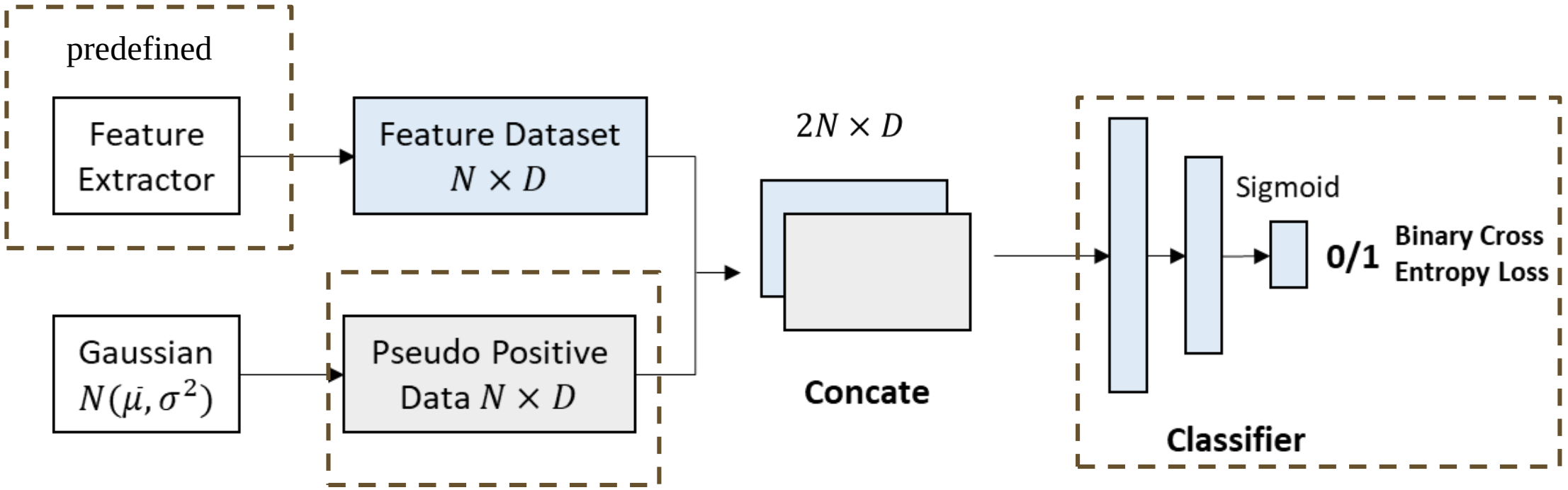
Detection Methodology

Detection Framework



Detection Methodology

One class classification



Detection framework evaluation

Offline detection

False positive rate: 8/1539 (0.52%)
False Negative rate: 2/490 (0.2%)

Online detection

False Positive Rate	False Negative Rate	Mean attack succeed time (s)	Mean detection time (s)	Mean time to attack succeed(s)
14/1539 (0.91%)	0/314 (0%)	2.096	1.600	0.497

Collaborators

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Acknowledgement

Thank you!

Questions?

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